## High-dimensional Sparse FFT

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March 1, 2019



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## Sparse Fourier Transforms (SFTs)

• We consider  $f(\mathbf{x}) = \sum_{\mathbf{n} \in \mathbb{N}^D} c_{\mathbf{n}} e^{2\pi i \mathbf{n} \cdot \mathbf{x}} \approx \sum_{\mathbf{n} \in \mathcal{S}} c_{\mathbf{n}} e^{2\pi i \mathbf{n} \cdot \mathbf{x}}$ where  $\mathbf{n} \in [-\frac{N}{2}, \frac{N}{2})^D \cap \mathbb{Z}^D$ , nonzero  $c_{\mathbf{n}} \in \mathbb{C}$ ,  $\mathbf{x} \in [0, 1)^D$  or  $\mathbb{R}^D$ ,  $|\mathcal{S}| = s \ll N^D$ .

- The Goal: Approximate f : [0,1)<sup>D</sup> → C using as few evaluations as possible, as quickly as possible.
- There exist 1D sparse Fourier transforms utilizing the ideas of phase-shift and isolation of the Fourier frequencies by taking modulo *p*, a prime number. Various transformations, projections, and rotations in the physical domain are taken to isolate the frequency vectors and approximate them entry-wise.

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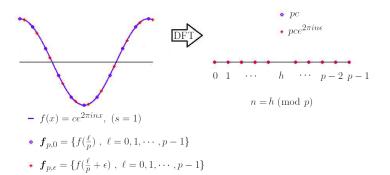
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## Description of 1D Sublinear Sparse Fourier Transform (D=1)



• p : prime number s.t.  $s , <math>\epsilon \leq 1/N$ 

• 
$$n = \frac{1}{2\pi\epsilon} \operatorname{Arg}\left(\frac{pce^{2\pi i\epsilon n}}{pc}\right), \ c = \frac{1}{p}pc$$

## Description of 1D Sublinear Sparse Fourier Transform

#### Test for Collision

• If there is only one frequency n congruent to  $h \mod p$ , then the following equation holds,

• 
$$\frac{|\mathcal{F}(\mathbf{f}_{p,\epsilon})[h]|}{|\mathcal{F}(\mathbf{f}_{p,0})[h]|} = 1.$$

- Otherwise, the equation does not hold for certain  $\epsilon$ .
- Average-case time complexity :  $\Theta(s \log s)$
- Average-case sampling complxity :  $\Theta(s)$

## 2D Sparse Fourier Transforms

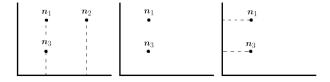


Figure: Process of the parallel projection method in 2D

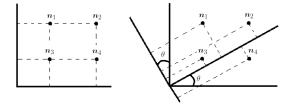


Figure: Worst case scenario in 2D and solving it through the tilting method

#### Performance of the tilting method in 2D

Let  $\mathbf{n} = (n_1, n_2) \in S \subset \left[-\frac{N}{2}, \frac{N}{2}\right)^2 \cap \mathbb{Z}^2$ . If  $\tan \theta = \frac{a}{b}$  such that c > b > a are Pythagorean triples where b > N and a are relative primes, then all  $(cn_1 \cos \theta - cn_2 \sin \theta, cn_1 \sin \theta + cn_2 \cos \theta)$  rotated by  $\theta$  does not collide with any other pair through the parallel projection. Thus, all rotated pairs can be identified by the parallel projection method.

- A finite series of rotations in 2D subspaces can be utilized to extend the tilting method to the general higher dimensional setting.
- Furthermore, if the number of dimensions, *D*, gets larger, the probability that the worst-case scenario happens converges to 0.

• 
$$f(\mathbf{x}) = \sum_{\mathbf{n}} c e^{2\pi i \mathbf{n} \cdot \mathbf{y}}$$

• 
$$c \in \mathbb{C}, n \in \left[-\frac{N}{2}, \frac{N}{2}\right)^4 \cap \mathbb{Z}^4 = \left(\left[-\frac{N}{2}, \frac{N}{2}\right)^2 \cap \mathbb{Z}^2\right)^2$$

• 
$$(n_1, n_2, n_3, n_4) \rightarrow (n_1 + Nn_2, n_3 + Nn_4) =: (\tilde{n}_1, \tilde{n}_2)$$

- The bandwidth of each entry is increased so that the chance of collision from projection decreased.
- Shifting size  $\epsilon$  should be smaller $\leq rac{1}{N^2}$

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#### Average-case runtime complexity

Assume  $N \ge 5s$  and there is no worst-case scenario. Let T(s) denote the runtime of the parallel projection method on a random signal setting. Then  $\mathbb{E}[T(s)] = \Theta(Ds \log s)$  and

$$\mathbb{P}[T(s) > \Theta(Ds \log s) + tDs \log s] \le 5^{-t}.$$

#### Average-case sampling complexity

Assume  $N \ge 5s$  and there is no worst-case scenario. Let S(s) denote the number of samples used in the parallel projection method on a random signal setting. Then  $\mathbb{E}[S(s)] = \Theta(Ds)$  and

$$\mathbb{P}[S(s) > \Theta(Ds) + tDs] \leq 5^{-t}.$$

#### Multiscale Algorithm for Noisy Data

f<sup>w,y</sup><sub>p,ε</sub>[j] = f<sup>w,y</sup><sub>p,ε</sub>[j] + z<sub>j</sub> where z<sub>j</sub>'s are i.i.d. complex Gaussian variables with mean 0 and variance σ<sup>2</sup>.
f<sup>w,y</sup><sub>p,ε</sub>[h] = f<sup>w,y</sup><sub>p,ε</sub>[h] + ẑ[h] where ẑ[h] = Σ<sup>p-1</sup><sub>j=0</sub> z<sub>j</sub>e<sup>-2πihj/p</sup>
E [f̂<sup>w,y</sup><sub>p,0</sub>[h]] = f̂<sup>w,y</sup><sub>p,0</sub>[h] and E [f̂<sup>w,y</sup><sub>p,0</sub>[h] - f̂<sup>w,y</sup><sub>p,0</sub>[h]|<sup>2</sup>] = pσ<sup>2</sup>
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For a non-collision n<sub>y</sub>,

$$\begin{aligned} \frac{\widehat{\widetilde{\mathbf{f}}}_{p,\epsilon}^{w,y}[h]}{\widehat{\widetilde{\mathbf{f}}}_{p,0}^{w,y}[h]} &= \frac{\widehat{\mathbf{f}}_{p,0}^{w,y}[h]e^{2\pi i n_y \epsilon} + \mathcal{O}(\sigma \sqrt{p})}{\widehat{\mathbf{f}}_{p,0}^{w,y}[h] + \mathcal{O}(\sigma \sqrt{p})} \\ &= e^{2\pi i n_y \epsilon} + \mathcal{O}(\sigma / c_{\mathbf{n}} \sqrt{p}) \end{aligned}$$

• 
$$\left\| \frac{1}{2\pi} \operatorname{Arg}\left( \frac{\widetilde{\mathbf{f}}_{p,e}^{w,y}[h]}{\widetilde{\mathbf{f}}_{p,0}^{w,y}[h]} \right) - n_y \epsilon \right\|_{\mathbb{Z}} \leq \mathcal{O}\left( \frac{\sigma}{|c_{\mathbf{n}}|\sqrt{\rho}} \right)$$

## Multiscale Frequency Estimation

• 
$$\epsilon_0 < 1/N, \epsilon_0 \widetilde{n}_y =_{\mathbb{Z}} \frac{1}{2\pi} \operatorname{Arg}\left(\frac{\widetilde{f}_{p,\epsilon_0}^{n,v}[h]}{\widetilde{f}_{p,0}^{n,v}[h]}\right)$$

•  $\widetilde{n}_y = n_y (\mod p)$ 

• 
$$\epsilon_1 > 1/N > \epsilon_0, b_1 = \frac{1}{2\pi} \operatorname{Arg}\left(\frac{\widetilde{\mathbf{f}}_{p,\epsilon_1}^{(r)}[h]}{\widetilde{\mathbf{f}}_{p,0}^{(w,y)}[h]}\right)$$

•  $b_1 \approx \epsilon_1 n_y (\text{mod } [-\frac{1}{2}, \frac{1}{2}))$ 

• 
$$\epsilon_1(n_y - \widetilde{n}_y) \approx (b_1 - \epsilon_1 \widetilde{n}_y) (\text{mod } [-\frac{1}{2}, \frac{1}{2}))$$

- $n_y (\widetilde{n}_y + (b_1 \epsilon_1 \widetilde{n}_y) (\text{mod } [-\frac{1}{2}, \frac{1}{2}))/\epsilon_1) = \mathcal{O}(\frac{\sigma}{\epsilon_1 \sqrt{p}})$
- This error correction process is iterated with progressively larger shifts  $\epsilon_i$ .

#### Multiscale Frequency Estimation

Let  $n \in \left[-\frac{N}{2}, \frac{N}{2}\right)$ . Let  $0 < \epsilon_0 < \epsilon_1 < \cdots < \epsilon_m$  and  $b_0, b_1, \cdots, b_m \in \mathbb{R}$  such that  $\|\epsilon_j n - b_j\|_{\mathbb{Z}} < \delta, 0 \le j \le m$ 

where  $0 < \delta \leq \frac{1}{4}$ . Assume that  $\epsilon_0 \leq \frac{1-2\delta}{N}$  and  $\beta_j := \epsilon_j/\epsilon_{j-1} \leq (1-2\delta)/(2\delta)$ . Then there exist  $d_0, d_1, \dots, d_m \in \mathbb{R}$ , each computable from  $\{\epsilon_j\}$  and  $\{b_j\}$ , such that

$$|\widetilde{n} - n| \leq rac{\delta}{\epsilon_0} \prod_{j=1}^m eta_j^{-1} ext{ where } \widetilde{n} := \sum_{j=0}^m rac{d_j}{\epsilon_j}.$$

#### Corollary 1

Assume that in the above theorem we have  $\beta_j = \beta$  where  $\beta \leq (1 - 2\delta)/(2\delta)$ , i.e.,  $\epsilon_j = \beta^j \epsilon_0$  for all j. Let  $m \geq \lfloor \log_\beta \frac{2\delta}{\epsilon_0} \rfloor + 1$ . Then

$$|\widetilde{n}-n|\leq rac{\delta}{\epsilon_0}eta^{-m}<rac{1}{2}.$$

## Average-case analysis of the multiscale approach

Let  $f^{z}(\mathbf{x}) = f(\mathbf{x}) + z(\mathbf{x})$ , where  $\hat{f}(\mathbf{n})$  is *s*-sparse with all frequencies satisfying  $\mathbf{n} \in S \subset [-N/2, N/2)^{D} \cap \mathbb{Z}^{D}$  and not forming any worst case scenario, and *z* is complex i.i.d. Gaussian noise of variance  $\sigma^{2}$ . Moreover, suppose that  $s > C(\beta(\beta + 1)c_{\min}\sigma)^{2}$  for some constant *C* (chosen carefully so that some technical assumptions are satisfied). The multiscale parallel projection method, given  $N, D, s, \beta$  with N > 5s and access to  $f^{z}(\mathbf{x})$  returns a list of *s* pairs ( $\hat{\mathbf{n}}, c_{\hat{\mathbf{n}}}$ ) such that (i) each  $\hat{\mathbf{n}} \in S$  and (ii) for each  $\hat{\mathbf{n}}$ , there is an  $\mathbf{n} \in S$  such that  $\mathbf{n} \in S$  with  $|c_{\mathbf{n}} - c_{\hat{\mathbf{n}}}| \leq C\sigma/\sqrt{s}$ . The average-case runtime and sampling complexity are

 $\Theta(sD \log s \log N)$  and  $\Theta(sD \log N)$ ,

respectively, over the class of random signals.

## Numerics

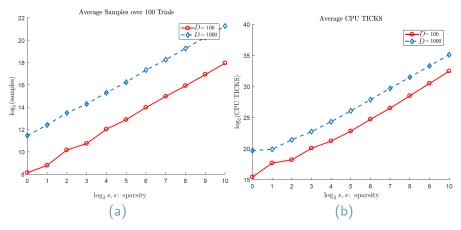


Figure: Average samples and average runtime (nosieless)

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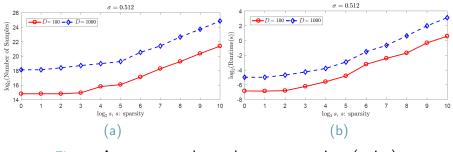
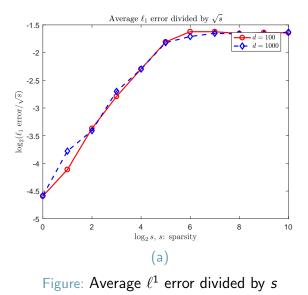


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Thanks for Listening!

# Questions?